

# Errata: State Controllability, Output Controllability and Stabilizability of Networks: A Symmetry Perspective

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**Abstract**—Prof. Kanat Camlibel kindly pointed out with an illuminating counterexample that the PBH test for output controllability quoted in Proposition 1 was incorrectly referenced. This PBH style test provides a sufficient condition for output uncontrollability and output unstabilizability not a necessary condition. We have corrected Proposition 1 accordingly and Theorem 2 which follows from Proposition 1.

## 4. OUTPUT CONTROLLABILITY AND STABILIZABILITY

**Proposition 1.** Popov-Belevitch-Hautus (PBH) test [1]. For  $A \in \mathbb{R}^{n \times n}$ ,  $B \in \mathbb{R}^{n \times m}$  and  $C \in \mathbb{R}^{p \times n}$ . Consider one or more of the following conditions on  $\lambda \in \mathbb{C}$  and  $v \in \mathbb{C}^n$ :

- (a)  $v^T B = 0$ ,
- (b)  $\exists q \in \mathbb{R}^p$  such that  $q^T C = v^T$  and
- (c)  $\text{Re}(\lambda) \geq 0$ .

Then there exists a left eigenvalue-eigenvector pair  $(\lambda, v)$  of  $A$  such that

- 1. (a)  $\iff (A, B)$  is uncontrollable.
- 2. (a) and (b)  $\implies (A, B, C)$  is output uncontrollable.

**(Only sufficient!!!)**

- 3. (a) and (c)  $\iff (A, B)$  is unstabilizable.
- 4. (a), (b) and (c)  $\implies (A, B, C)$  is output unstabilizable.

**(Only sufficient!!!)**

**Theorem 2.** For  $A$  diagonalizable and  $C$  full row rank, consider one or more of the following conditions on a  $P \in \mathbb{R}^{n \times n}$ :

- (a)  $P \neq I$ ,  $AP = PA$  and  $PB = B$ .
- (b)  $P = I - ZC$ , for some  $Z \in \mathbb{R}^{n \times p}$ .
- (c)  $\frac{1}{2}(P + P^T) \preceq I$  and  $PA + (PA)^T \preceq A + A^T$ .

Then there exists a  $P \in \mathbb{C}^{n \times n}$  such that

- 1. (a)  $\iff (A, B)$  is uncontrollable.
- 2. (a) and (b)  $\implies (A, B, C)$  is output uncontrollable.

**(Only sufficient!!!)**

- 3. (a) and (c)  $\implies (A, B)$  is unstabilizable.
  - 4. (a), (b) and (c)  $\implies (A, B, C)$  is output unstabilizable.
- Further, for symmetric  $A$ , the statements 3. ~~and 4.~~ are necessary and sufficient.

## REFERENCES

- [1] T. Kailath, *Linear Systems*. Upper Saddle River: Prentice Hall, 1979.